Reg. No.							

**Question Paper Code** 

11472

# B.E. / B.Tech. - DEGREE EXAMINATIONS, NOV/DEC 2022

Seventh Semester

## Mechanical Engineering

(Common to Production Engineering)

## **ME8791 - MECHATRONICS**

(Regulations 2017)

Duration: 3 Hours

each group.

Max. Marks: 100

## $PART - A (10 \times 2 = 20 Marks)$

Answer ALL Questions

1.	What are the basic functions of control system?	Marks, K-Level, CO 2,K1,CO1
2.	What is the basic principle of thermocouple?	· 2,K1,CO1
3.	Define Timing diagram.	2,K1,CO2
4.	What are the special function registers in 8051?	2,K1,CO2
5.	What is the need for interfacing?	2,K1,CO3
6.	Explain the various modes of 8255.	2,K2,CO3
7.	What are counters?	2,K1,CO4
8.	Draw and explain NOR logic function using ladder diagram.	2,K1,CO4
9.	List the properties of a stepper motor.	2,K2,CO5
10.	State the characteristics of servomotor.	2.K1,CO5

## PART - B $(5 \times 13 = 65 \text{ Marks})$

Answer ALL Questions

11. a) What is sequential controller? Explain how a microprocessor based 13, K2,C01 controller operates a washing machine.

#### OR

- b) Explain in detail about the following sensors

  (i) Thermistors.

  (ii) Bimetallic strips.

  7,K2,C01

  6,K2,C01
- 12. a) Explain the addressing modes of 8085 with minimum four examples in 13,K2,CO2

#### OR

b) With neat sketch explain the architecture of 8085 Microprocessor. 13,K2,CO2

K1 - Remember; K2 - Understand; K3 - Apply; K4 - Analyze; K5 - Evaluate; K6 - Create

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13. a) Design a 7 segment LED display interfacing with 8051.

OR

13, K2, C03

b) Explain the Architecture of 8255 PPI. 13,K2,C03

- 14. a) Explain in detail about the following with suitable ladder diagram: 13,K2,C04
  - (i) Latching (ii) Counters
  - (iii) Jump control

OR

- b) Interpret how logic functions can be formed with ladder diagram. 13,K2,C04
- 15. a) What are the types of stepper motors? Explain with suitable diagram 13,K2,C05 about permanent magnet stepper motor with its advantages and disadvantages.

OR

- b) (i) What are the differences between stepper motor and servo motor? 7,K2,C05
  - (ii) Illustrate the advantages and disadvantages of stepper motor.

6,K2,CO5

## PART - C $(1 \times 15 = 15 \text{ Marks})$

16. a) What are the various stages in designing a mechatronics system? 15,K2,C06 Explain.

OR

b) Discuss the mechatronics design of an automatic car parking system 15,K2,C06 with suitable diagram.