

Reg. No.

Question Paper Code

21309

M.E. / M.Tech. - DEGREE EXAMINATIONS, NOV/DEC 2022

First Semester

M.E. - CAD/CAM

20PCDMA101 - OPTIMIZATION TECHNIQUES IN DESIGN

(Regulations 2020)

Duration: 3 Hours

Max. Marks: 100

PART - A (10 × 2 = 20 Marks)

Answer ALL Questions

- | | <i>Marks,
K-Level, CO</i> |
|-------------------------------------------------------------------------------------|-------------------------------|
| 1. Explain the principles of optimization and write its elements. | 2,K2,CO1 |
| 2. Explain unconstrained minimization problem and write few methods for solving it. | 2,K2,CO1 |
| 3. Explain geometric interpretation of the reduced gradient. | 2,K2,CO2 |
| 4. Define Multi stage optimization. | 2,K1,CO2 |
| 5. Explain why are the components numbered in reverse order in dynamic Programming. | 2,K2,CO3 |
| 6. Explain about a neural network. | 2,K2,CO3 |
| 7. Define longitudinal load. Give any two examples. | 2,K1,CO4 |
| 8. List the various stresses induced in shaft. | 2,K1,CO4 |
| 9. Define dynamics. | 2,K1,CO5 |
| 10. Explain about mechanism. | 2,K2,CO5 |

PART - B (5 × 13 = 65 Marks)

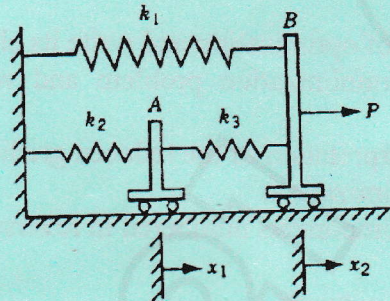
Answer ALL Questions

11. a) Find the minimum of $f = \lambda^5 - 5\lambda^3 - 20\lambda + 5$ by the cubic interpolation method. 13,K3,CO1
- OR**
- b) Prove that a convex function is unimodal. 13,K3,CO1
12. a) Solve the following LP problem by Dynamic Programming: 13,K3,CO2
 Maximize $f(x_1, x_2) = 10x_1 + 8x_2$
 Subject to $2x_1 + x_2 \leq 25$
 $3x_1 + 2x_2 \leq 45$
 $x_2 \leq 10$
- And
- $x_1 \geq 0, \quad x_2 \geq 0$
- OR**
- b) Explain in detail the relation between the sequential quadratic programming method and the Lagrangian function 13,K2,CO2

13. a) Two discrete fuzzy sets, A and B are defined as follows: 13.K3.CO3
 $A = \{(60, 0.1) (62, 0.5) (64, 0.7) (66, 0.9) (68, 1.0) (70, 0.8)\}$
 $B = \{(60, 0.0) (62, 0.2) (64, 0.4) (66, 0.8) (68, 0.9) (70, 1.0)\}$
 Determine the union and intersection of these sets

OR

- b) Find the minimum of the following function using simulated annealing: $f(X) = 6x_1^2 + 2x_2^2 - x_1 - 2x_2 - 6x_1x_2$. Assume suitable parameters and show detailed calculations for 2 iterations. 13.K3.CO3
14. a) Figure below shows two frictionless rigid bodies (carts) A and B connected by three linear elastic springs having spring constants k_1 , k_2 and k_3 . The springs are at their natural positions when the applied force P is zero. Find the optimal solution of displacements x_1 and x_2 under the force P by using the principle of minimum potential energy. 13.K3.CO4



OR

- b) (i) State the relation for efficiency of a screw jack and identify the contributing factors. Also find the optimal value of each factor. 8.K3.CO4
 (ii) During the design of structural members, safety is more important than optimization. Comment. 5.K3.CO4
15. a) Formulate an optimization problem and Find the link lengths of the four-bar linkage for minimum structural error. 13.K3.CO5

OR

- b) Write about vibration absorbers and the need of optimization in their design. 13.K2.CO5

PART - C (1 × 15 = 15 Marks)

16. a) Minimize the function 15.K3.CO1

$$f(\lambda) = 0.65 - \frac{0.75}{1+\lambda^2} - 0.65 \lambda \tan^{-1} \frac{1}{\lambda}$$

Using the Golden Section method with $n = 6$. Formulate the optimization problem and suggest the suitable solution techniques.

OR

- b) Find the minimum of the function 15.K3.CO1

$$f(\lambda) = 0.65 - \frac{0.75}{1+\lambda^2} - 0.65 \lambda \tan^{-1} \frac{1}{\lambda}$$

by Newton Raphson method with the string point $\lambda_1 = 0.1$