					Re	g. No.											
		Question Paper Code			ode	12168					1 1						
Dur	ation	B.E. / B.T 20AIP	ech DE Artificia C601 - RO	GREE EX Sixth I Intellige DBOTICS (Regulat	AM Sen nce : PR(INATIOnester and Da OCESS (2020)	ONS ta Sc AU'	, NC ienc FOI	DV ce MA	/ DI	EC 2 DN May	023 × N	} /arl	zs• 1(00		
Dui	anon	1. J 110015	PAI	RT - A (10	× 2	= 20 M	arks)			10102	X • 1	lair	13. 10	10		
			1 7 1	Answer A		Duestion	ai Ks IS)									
1. 2.	Wh Def	at are the risk	and challe	enges of RI	PA?	<i>u</i> uostioi								Mar K-Lev 2,K1, 2,K1,	ks, v el, CO CO1 CO1		
3.	Но	w to import a	new name	spaces?										2,K2,CO2			
4.	Wh	What are flow charts and when it is used?									2,K1,CO2						
5.	What are the structure of Selector and the format of each node?									2,K2,CO3							
6.	Difference between input method and output method									2,K2,CO3							
7.	What are the characteristics of actuating systems?									2,K2,CO4							
8	What is a sensor?									2,K1,CO4							
9	How robotics and automation plays an important role in Industry 4.02									2,K2,CO6							
10.	How robots assist the medical procedures?									2,K2,	CO6						
			PA	RT - B (5 > Answer Al	< 13 LL (= 65 M Juestior	arks)									
11.	a)	Describe va performance	rious met testing.	hods to ju	ıdge	the su	itabi	lity	of	rob	ot u	sin	g	13,K2	,CO1		
				0	R												
	b)	Compare an	d contrast	PDD and S	DD	with the	eir ke	ey co	omj	pone	ents.			13,K2	,CO1		
12.	a)	Write in det	ail about a	utomated st Ol	torag R	ge/ retrie	evals	syste	ems	5.				13,K2	,CO2		
	b)	List the pane	els availabl	le in RPA t	cool a	and exp	lain i	n de	etai	1.				13,K2	,CO2		
13.	a)	Explain UiP	ath recordi	ng and its O l	type R	s in deta	ail.							13,K2	, <i>CO3</i>		
	b)	Illustrate Ui	Path PDF 1	Data Extra	ction	in deta	il.							13,K2	, <i>CO3</i>		

K1 – Remember; K2 – Understand; K3 – Apply; K4 – Analyze; K5 – Evaluate; K6 – Create 1 12168

14.	a)	Justify the working of touch and tactile sensor with an example.	13,K2,CO4	
		OR		
	b)	Explain the working of force and pressure sensor with neat diagram.	13,K2,CO4	
15.	a)	(i) Write short notes on applications of robotics and automation.		
		(ii) Write about micro and nano robots.		
		OR		
	b)	Enumerate the uses of robots in household applications and elaborate	13,K2,CO6	

PART - C (1 × 15 = 15 Marks)

16. a) Justify Singularities and Jacobian of Robotics using mathematical ^{15,K2,CO5} equations.

OR

with an example.

b) Describe in detail about Trajectory Planning for robot manipulators. 15,K2,CO5