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Question Paper Code	12594
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**B.E. / B.Tech. - DEGREE EXAMINATIONS, APRIL / MAY 2024**

Seventh Semester

**Electrical and Electronics Engineering**

**20EEL713 - SPECIAL ELECTRICAL MACHINES**

Regulations - 2020

Duration: 3 Hours

Max. Marks: 100

**PART - A (10 × 2 = 20 Marks)**

Answer ALL Questions

- |  | Marks | K-<br>Level | CO  |
|--|-------|-------------|-----|
| 1. Define step angle.  | 2     | K1          | CO1 |
| 2. What is meant by pull out range?  | 2     | K1          | CO1 |
| 3. Give basic features of Switched Reluctance motor.                         | 2     | K1          | CO2 |
| 4. What are the merits of classic converter in SRM?                          | 2     | K1          | CO2 |
| 5. List the permanent magnet materials used in PMBLDC motors.                | 2     | K1          | CO3 |
| 6. Name the position sensors that are used for PMBLDC motor.                 | 2     | K1          | CO3 |
| 7. Define load angle.  | 2     | K1          | CO4 |
| 8. Summarize the distribution factor for PMSM.                               | 2     | K2          | CO4 |
| 9. Describe in short about SYNREL motors.                                    | 2     | K2          | CO5 |
| 10. Outline the various design parameters of a synchronous reluctance motor. | 2     | K2          | CO5 |

**PART - B (5 × 13 = 65 Marks)**

Answer ALL Questions

- |   |    |    |     |
|---|----|----|-----|
| 11. a) Draw and explain in detail the static and dynamic characteristics of stepper motor.        | 13 | K2 | CO1 |
| <b>OR</b>   |    |    |     |
| b) Summarize about the suppressor circuits for stepper motor.                                     | 13 | K2 | CO1 |
| 12. a) Explain the construction and working of Switched Reluctance motor.                         | 13 | K2 | CO2 |
| <b>OR</b>   |    |    |     |
| b) Derive the voltage and torque equation of SRM.   | 13 | K2 | CO2 |
| 13. a) Explain in detail about various types and working of PMBLDC motor with necessary diagrams. | 13 | K2 | CO3 |
| <b>OR</b>   |    |    |     |
| b) Identify appropriate power controllers for PMBLDC motor and explain with neat diagram.         | 13 | K2 | CO3 |

14. a) Derive the expression for power input and torque of a PMSM. Explain how its torque speed characteristics are obtained. 13 K2 CO4

**OR**

- b) A 3  $\phi$ , 4 pole, brushless PM rotor has 36 stator slots. Each phase winding is made up of three coils per pole with 10 turns per coil. The coil span = 7 slots. If the fundamental component of magnet flux is 1.8mWb. Estimate the open circuit phase emf (Eq) at 3000 rpm. 13 K2 CO4
15. a) Compare a reluctance motor with an equivalent induction motor and list out the merits and demerits of reluctance motor over induction motor. 13 K2 CO5
- OR**
- b) i) Distinguish between Axial and Radial air gap motors. 7 K2 CO5  
ii) List out the applications of synchronous reluctance motor. 6 K2 CO5

**PART - C (1  $\times$  15 = 15 Marks)**

16. a) A Variable Reluctance stepper motor has a step angle of 3°, Determine the following: (i) Resolution. (ii) Number of steps per shaft to make 10 revolutions (iii) Shaft speed if stepping frequency is 2400pulse/sec. 15 K3 CO1
- OR**
- b) Develop the various modes of operation of permanent magnet stepper motor with neat diagram. 15 K3 CO1