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Question Paper Code	13017
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B.E. / B.Tech. - DEGREE EXAMINATIONS, NOV / DEC 2024

Sixth Semester

Mechanical Engineering

20MEPC603 - MECHATRONICS

Regulations - 2020

Duration: 3 Hours

Max. Marks: 100

PART - A (MCQ) (20 × 1 = 20 Marks)

Answer ALL Questions

	<i>Marks</i>	<i>K-Level</i>	<i>CO</i>
1. Which of the following is a primary function of a sensor? (a) Convert mechanical energy to electrical energy (b) Convert electrical energy to mechanical energy (c) Store electrical energy (d) Amplify electrical signals	1	K1	CO1
2. A potentiometer is primarily used to _____. (a) Measure electrical resistance (b) Control voltage levels in a circuit (c) Increase the current flow (d) Store electric charge	1	K1	CO1
3. What type of light sensor works by varying its electrical resistance according to the amount of light falling on it? (a) Photovoltaic cell (b) Thermocouple (c) Phototransistor (d) Light Dependent Resistor (LDR)	1	K2	CO1
4. How many T-states are typically required for the opcode fetch cycle in the 8085 microprocessors? (a) 2 T-states (b) 3 T-states (c) 4 T-states (d) 6 T-states	1	K1	CO2
5. What is the purpose of the 'WAIT' state in an 8085-timing diagram? (a) To reset the microprocessor (b) To halt the clock signal temporarily (c) To synchronize slower peripherals with the microprocessor (d) To end the machine cycle	1	K1	CO2
6. Which of the following registers is not a part of the 8085 microprocessor architecture? (a) Accumulator (A) (b) Stack Pointer (SP) (c) Program Counter (PC) (d) Instruction Queue (IQ)	1	K2	CO2
7. Which signal is used to select the 8255 chip for communication with the processor? (a) RD (b) WR (c) CS (d) ALE	1	K1	CO3
8. In keyboard interfacing, what is the common method used to detect key presses? (a) Analog signal processing (b) Interrupt-driven I/O (c) Polling method (d) Direct memory access	1	K1	CO3
9. For a 7-segment LED display interfaced via 8255, how many data lines are typically required? (a) 4 (b) 7 (c) 8 (d) 9	1	K1	CO3
10. What type of programming language is most commonly used for programming PLCs? (a) Python (b) Ladder Logic (c) C++ (d) Assembly Language	1	K1	CO4
11. What type of output is controlled by a PLC to operate devices like motors and lights? (a) Digital Output (b) Analog Output (c) Sequential Output (d) Continuous Output	1	K2	CO4
12. In data handling, which of the following is typically used for handling complex data structures in PLCs? (a) Arrays (b) Strings (c) Booleans (d) Integers	1	K1	CO4

13. What is a primary characteristic of a Hybrid Stepper Motor? 1 K1 CO5
 (a) Uses permanent magnets and a toothed rotor
 (b) Provides continuous rotation without steps
 (c) Operates only in open-loop systems
 (d) Has low torque at high speeds
14. Which type of motor generally includes a feedback mechanism for closed-loop control? 1 K1 CO5
 (a) Stepper Motor (b) DC Motor
 (c) AC Servo Motor (d) Variable Reluctance Stepper Motor
15. Which of the following is an advantage of stepper motors? 1 K1 CO5
 (a) High torque at high speeds (b) Precise position control without feedback
 (c) High energy efficiency (d) Continuous rotation capability
16. In which application are stepper motors most commonly used? 1 K2 CO5
 (a) High-speed conveyor systems (b) Precision positioning systems like 3D printers
 (c) High-torque robotic arms (d) Electric vehicles
17. Which of the following mechatronic systems is primarily used in manufacturing for precision machining? 1 K2 CO6
 (a) Electric bicycles (b) Robotic welding systems
 (c) Smart refrigerators (d) Home automation systems
18. In pick and place robots, what type of end effector is typically used for grasping objects? 1 K1 CO6
 (a) Drill (b) Gripper (c) Welding tool (d) Cutter
19. In an EMS, what role does the Engine Control Unit (ECU) play? 1 K1 CO6
 (a) It physically adjusts the throttle position
 (b) It stores all diagnostic trouble codes
 (c) It processes data from various sensors to control engine functions
 (d) It only monitors the exhaust emissions
20. Which sensor type is commonly used in automatic car park barriers to detect the presence of a vehicle? 1 K1 CO6
 (a) Ultrasonic sensor (b) Infrared sensor (c) Pressure sensor (d) All of the above

PART - B (10 × 2 = 20 Marks)

Answer ALL Questions

21. What is the need of Mechatronics? 2 K1 CO1
22. List the Characteristics of Sensor. 2 K1 CO1
23. Classify the types of addressing modes of 8085. 2 K2 CO2
24. Summarize the advantages of microcontroller over microprocessor. 2 K2 CO2
25. Compare ADC and DAC interface. 2 K2 CO3
26. What are the various modes of 8255? 2 K1 CO3
27. Why is PLC preferred over PC in factories? 2 K1 CO4
28. Mention any two applications of Counters. 2 K1 CO4
29. Distinguish between stepper motor and Servo motors. 2 K2 CO5
30. What are the sensors used in engine management system? 2 K1 CO6

PART - C (6 × 10 = 60 Marks)

Answer ALL Questions

31. a) Interpret the various elements of a closed loop system in automatic water level controller and describe their functions. 10 K2 CO1
 OR
 b) Explain in detail about the following sensors:
 (i) Thermocouple 5 K2 CO1
 (ii) Hall effect sensor 5 K2 CO1
32. a) Illustrate about the pin configuration of 8085 microprocessor with a suitable sketch. 10 K2 CO2

OR

b) Explain different addressing modes of 8051 microcontroller. 10 K2 CO2

33. a) Describe the 8255 Programmable Peripheral Interface's architecture. 10 K2 CO3

OR

b) Explain a traffic light controller using 8255 microcontrollers. 10 K2 CO3

34. a) Write short notes on: 10 K2 CO4
(i) Timers and counters
(ii) Internal relays

OR

b) Summarize the mnemonics codes for various logic gates. 10 K2 CO4

35. a) Explain the construction and working principle of stepper motor 10 K2 CO5

OR

b) Explain in detail about construction and working of closed loop servo system with suitable example of servomotor control system. 10 K2 CO5

36. a) Explain the mechatronics systems in the industrial application of pick and place robot. 10 K2 CO6

OR

b) Explain the factors to be considered while selecting a PLC for mechatronics system design. 10 K2 CO6