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Question Paper Code	12696
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M.E. / M.Tech. - DEGREE EXAMINATIONS, APRIL / MAY 2024

First Semester

M.E - Power Electronics and Drives

20PPEPC105 - SPECIAL MACHINES AND CONTROLLERS

Regulations - 2020

Duration: 3 Hours

Max. Marks: 100

PART - A (10 × 2 = 20 Marks)

Answer ALL Questions

- | | Marks | K-
Level | CO |
|--|-------|-------------|-----|
| 1. Mention the some applications of PMBL DC motor. | 2 | K1 | CO1 |
| 2. List out the various kinds of permanent magnets. | 2 | K1 | CO1 |
| 3. Compare PMSM and PMBLDC motors. | 2 | K2 | CO2 |
| 4. Write the torque equation of the SynRM. | 2 | K1 | CO2 |
| 5. What is basic principle of operation of switched reluctance motor? | 2 | K1 | CO3 |
| 6. Give the expression for torque of a Switched Reluctance motor. | 2 | K1 | CO3 |
| 7. Mention the different types of stepper motor. | 2 | K1 | CO4 |
| 8. Define maximum starting torque and maximum starting frequency of stepper motor. | 2 | K1 | CO4 |
| 9. Write the expression of Thrust force of LIM. | 2 | K1 | CO5 |
| 10. What is the necessity of having laminated yoke in an ac series motor? | 2 | K1 | CO5 |

PART - B (5 × 13 = 65 Marks)

Answer ALL Questions

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|--|----|----|-----|
| 11. a) Estimate the EMF equations of the permanent magnet brushless DC motor. | 13 | K2 | CO1 |
| OR | | | |
| b) Explain in detail the various rotor position sensors used in permanent magnet brushless DC Motor. | 13 | K2 | CO1 |
| 12. a) Explain the construction and working principle of operation of PMSM. | 13 | K2 | CO2 |
| OR | | | |
| b) Explain the working of variable reluctance type and hybrid type SynRM. | 13 | K2 | CO2 |
| 13. a) Explain the construction and working of Switched Reluctance motor. | 13 | K2 | CO3 |

OR

K1 – Remember; K2 – Understand; K3 – Apply; K4 – Analyze; K5 – Evaluate; K6 – Create

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b) Draw and explain torque – speed characteristics of Switched Reluctance motor. 13 K2 CO3

14. a) Illustrate construction and various modes of excitation of Permanent Magnet stepper Motor. 13 K2 CO4

OR

b) Derive the mechanism of torque production in VR stepper motor. 13 K2 CO4

15. a) Illustrate the construction and working principle of hysteresis motor. 13 K2 CO5

OR

b) Explain the performance characteristics of Linear Induction motor and hysteresis motor. 13 K2 CO5

PART - C (1 × 15 = 15 Marks)

16. a) Discuss in detail about different types of power driver circuits for stepper motor. 15 K2 CO4

OR

b) Describe the various power controller circuits to Switched Reluctance motor and explain the operation of any one scheme with suitable circuit diagram. 15 K2 CO3