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|-----|--|---|----|-----|
| 15. | Compute the probability of error for a BPSK system in AWGN using the Q-function. | 2 | K2 | CO3 |
| 16. | Explain how fading influences the performance of digital modulation schemes. | 2 | K2 | CO3 |
| 17. | Distinguish between flat and frequency-selective fading channels. | 2 | K2 | CO4 |
| 18. | Outline the role of diversity techniques in improving receiver performance under fading. | 2 | K2 | CO4 |
| 19. | Specify the need for carrier phase estimation in digital receivers. | 2 | K2 | CO5 |
| 20. | Infer the process of symbol timing recovery using a timing error detector. | 2 | K2 | CO5 |
| 21. | Compare the convergence characteristics of the LMS and Zero-Forcing algorithms. | 2 | K2 | CO6 |
| 22. | State the main advantage of a Decision-Feedback Equalizer (DFE) over a linear equalizer. | 2 | K1 | CO6 |

PART - C (6 × 11 = 66 Marks)

Answer ALL Questions

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|-----|---|----|----|-----|
| 23. | a) Explain the concept of signal space representation for digital modulation schemes. Illustrate with BPSK and QPSK. | 11 | K2 | CO1 |
| | OR | | | |
| | b) Illustrate the spectral characteristics of ASK, FSK, and PSK and their bandwidth efficiency. | 11 | K2 | CO1 |
| 24. | a) With a neat diagram, explain the structure and operation of an optimum receiver for AWGN channel using a matched filter. | 11 | K2 | CO2 |
| | OR | | | |
| | b) Derive the expression for probability of error in maximum likelihood sequence detection for binary signaling over AWGN channel. | 11 | K2 | CO2 |
| 25. | a) Summarize the performance of M-ary orthogonal signaling with diversity. | 11 | K2 | CO3 |
| | OR | | | |
| | b) Illustrate the benefits of coding for Rayleigh fading channel with binary PSK modulation. | 11 | K2 | CO3 |
| 26. | a) Explain Rayleigh and Rician statistical models for characterizing fading channels. | 11 | K2 | CO4 |
| | OR | | | |
| | b) Infer the performance of coded waveforms in frequency selective fading channels. | 11 | K2 | CO4 |
| 27. | a) Compare and justify the suitability of data-aided and non-data-aided synchronization methods for high-speed digital communication receivers. | 11 | K2 | CO5 |
| | OR | | | |
| | b) Illustrate maximum likelihood and non-decision directed timing estimation methods with necessary equations. | 11 | K2 | CO5 |
| 28. | a) Explain adaptive decision-feedback equalizer for digital communication systems and justify the choice of adaptation algorithm, filter structure, and performance criteria. | 11 | K2 | CO6 |
| | OR | | | |
| | b) Illustrate the operation of the Zero-Forcing equalizer. Explain how it removes ISI and explain its limitations in noisy channels. | 11 | K2 | CO6 |