Question Paper Code 13593

B.E. / **B.Tech.** - **DEGREE EXAMINATIONS, APRIL** / MAY 2025

Sixth Semester

Electronics and Instrumentation Engineering

(Common to Instrumentation and Control Engineering)

20EIPC602 - EMBEDDED SYSTEMS

Regulations - 2020

ט	uration: 3 Hours	ax. Ma	rks: 1	UU	
	$PART - A (MCQ) (10 \times 1 = 10 Marks)$	Marks	K – Level	co	
	Answer ALL Questions				
1.	Which of these designs considers both the software and hardware during the embedded	d^{-1}	<i>K1</i>	CO1	
	design?				
	(a) Peripheral Design (b) Platform-Based Co design				
	(c) Software/Hardware Design (d) Memory Design				
2.	Restarting a Watchdog timer is known as	1	K1	CO1	
	(a) Pushing (b) Pulling (c) Kicking (d) Picking				
3.	Which of the following can be used for long distance communication?	1	K1	CO2	
	(a) I ² C (b) Parallel Port (c) SPI (d) RS232				
4.	(a) I ² C (b) Parallel Port (c) SPI (d) RS232 Two wire interface is also called as (a) UART (b) SPI (c) I ² C (d) USART	1	K1	CO2	
	(a) UART (b) SPI (c) I^2C (d) USART				
5.	What does a Data Flow Graph (DFG) primarily model?	1	<i>K</i> 2	CO3	
	(a) The control flow of a program (b) The data flow within a system				
	(c) The state transitions of a system (d) The sequence of operations in a workflow				
6.	What is the primary purpose of a state machine model?	1	<i>K</i> 2	CO3	
	(a) To model data flow within a system				
	(b) To describe the behavior of a system as it transitions between states				
	(c) To represent the hierarchical structure of a system				
	(d) To visualize the sequence of operations in a workflow				
7.	Which of the following is the primary advantage of using an RTOS in embedded system	n 1	<i>K</i> 2	CO4	
	design?				
	(a) Increased power consumption				
	(b) Reduced complexity of software development				
	(c) Improved real-time performance and predictability				
	(d) Simpler hardware interface requirements				
8.	What is the purpose of a task scheduler in an RTOS?	1	K1	CO4	
	(a) To manage the physical memory of the system.				
	(b) To manage the flow of data between different devices.				
	(c) To determine which task should run and when.				
	(d) To handle all the interrupts generated by the system.				
9.	What is the primary function of the IoT device's embedded system?	1	<i>K</i> 2	CO5	
	(a) To facilitate useful experiences as part of the device's interface.				
	(b) To facilitate communication between the device and its end user.				
	(c) To facilitate communication between the sensor and the network.				
	(d) To facilitate faster performance, depending on network connection.	_			
10.	Which of the following is not an IoT device?	1	<i>K1</i>	CO5	
	(a) Table (b) Laptop c) Arduino (d) Tablet				

PART - B $(12 \times 2 = 24 \text{ Marks})$

Answer ALL Questions

		Answer ALL Questions			
11.	Expla	in the functional requirements of Embedded System.	2	K2	CO1
12.	How e	embedded systems are classified?	2	K1	CO1
13.	Discus	ss the two essential units of a processor on an embedded system.	2	K2	CO1
14.	Differ	entiate between Synchronous and Asynchronous communication.	2	K2	CO2
15.	List or	at the features of RS-485 standard.	2	K1	CO2
16.	Expla	in about CAN bus. Where is it used?	2	K2	CO2
17.	What	are the objectives of EDLC?	2	K1	CO3
18.	Define	e sequential Programming Model.	2	<i>K1</i>	CO3
19.	Explain the need of RTOS in the Embedded system.				CO4
20.	What	is Task scheduler?	2	K1	CO4
21.	Comp (M2M	are the difference between the Internet of Things (IoT) and Machine to Machine ().	2	K2	CO5
22.	What	are the major Privacy and Security Issues in case of Internet Of Things?	2	K1	CO5
		PART - C $(6 \times 11 = 66 \text{ Marks})$ Answer ALL Questions			
23.	a) (i)	Illustrate with neat diagram about the functional unit of embedded processor.	8	K2	CO1
	, , ,	Write the types of timers and explain any two types of timers. OR	3	K2	CO1
	b)	Describe in detail about the data transfer mechanism using DMA in Embedded System.	11	K2	CO1
24.	a) (i)	Define port and explain the various types of serial and parallel ports.	7	<i>K</i> 2	CO2
		What is SPI protocol and describe its interface? OR	4	K2	CO2
	b)	Describe the architecture, message formats and error detection in CAN protocol.	11	K2	CO2
25.	a)	Write the steps involved in describing a system's behavior as a state Machine. OR	11	K2	CO3
	b)	Explain in detail about the different phases of EDLC with necessary diagram.	11	K2	CO3
26.	a)	Explain any three types of inter process communication functions between the tasks.	11	K2	CO4
	b)	OR	11	K2	CO4
	b)	Discuss about pre-emptive and non pre-emptive scheduling with suitable diagram.	11	112	001
27.	a)	Explain in detail about the various IoT protocol stacks used in the layered architecture.	11	K2	CO5
	b)	OR Explain the Physical Design of IoT and Logical Design of IoT with function block diagram.	11	K2	CO5
28.	a) (i)	Explain in detail about semaphores and its applications.	6	K2	CO4
_0.	, , ,	Illustrate with suitable diagram about the IoT architecture and its functional element.	5	K2	CO5
	b) (i)	OR Explain in detail about priority inversion	6	K2	CO4
		Explain in detail about priority inversion. Discuss about IoT based Smart Irrigation with examples.	5	K2	CO5
	(11)	2 is the about for outset officer frightion with examples.			