Reg. No.								

Question Paper Code

13422

B.E. / B.Tech. - DEGREE EXAMINATIONS, APRIL / MAY 2025

Seventh Semester

Electronics and Instrumentation Engineering 20ICPC701 - LOGIC AND DISTRIBUTED CONTROL SYSTEM

Regulations - 2020

Dı	Max. Marks: 100				
	$PART - A (MCQ) (10 \times 1 = 10 Marks)$	Ml	<i>K</i> –	CO	
	Marks	Level	CO		
1.	What type of signal does a discrete input module handle?	1	<i>K1</i>	CO1	
	(a) Continuous voltage (b) Digital signals (c) Analog signals (d) Temperature signals				
2.	What does an analog input module typically convert?	1	<i>K1</i>	CO1	
	(a) Analog signals to digital signals (b) Digital signals to analog signals				
	(c) Voltage to current (d) Temperature to pressure				
3.	What type of diagram in Functional Block Diagram is most similar to in terms of visual	1	K1	CO2	
	representation?				
	(a) Flowchart (b) Gantt chart (c) P&ID (d) Bar chart				
4.	What is the primary advantage of using Sequential Function Chart in PLC programming?	1	<i>K1</i>	CO2	
	(a) Simplifies complex sequential operations				
	(b) Provides a text-based approach to programming				
	(c) Optimizes memory usage				
	(d) Reduces execution time			~~~	
5.	In a Data acquisition system, which component is responsible for amplifying or modifying	1	K1	CO3	
	signals before conversion?				
	(a) Analog-to-Digital Converter (b) Signal Conditioner				
_	(c) Data Processing Unit (d) Data Storage	7	1/1	G02	
6.	In SCADA systems, which communication protocol is commonly used for data exchange	1	<i>K1</i>	CO3	
	between devices?				
7	(a) HTTP (b) Modbus (c) FTP (d) SMTP	1	K1	CO4	
7.	Distributed Control Systems evolved primarily to overcome limitations associated with	1	K1	C <i>04</i>	
0	(a) PLCs (b) SCADA systems (c) Single-loop controllers (d) All of the above	1	K1	CO4	
8.	The communication backbone of a DCS is typically (a) Ethernet based (b) Social based (c) W: Ethernet based (d) Infrared based	1	ΚI	CO4	
9.	(a) Ethernet-based (b) Serial-based (c) Wi-Fi-based (d) Infrared-based Plant-wide control refers to	1	K1	CO5	
9.	(a) Control of individual units in isolation	•	***	005	
	(a) Condition of individual units in isolation (b) Coordination and control of multiple units across a plant				
	(c) Supervisory control at the enterprise level				
	(d) Remote monitoring without control actions				
10.	In IoT, which protocol is commonly used for low-power, short-range communication?	1	K1	CO5	
10.	(a) TCP/IP (b) Zigbee (c) Ethernet (d) HTTP				
	(a) 101/11 (b) 111/11 (c) 211/11 (c) 111/11				
	$PART - B (12 \times 2 = 24 Marks)$				
	Answer ALL Questions				
11.	What is the function of an optical isolator?	2	<i>K1</i>	CO1	
12.	Define Scan cycle.	2	K1	CO1	
13.	Mention the difference between ON delay and OFF delay timer.	2	K1	CO1	
14.	2	K2	CO2		
	Mention the structured text instruction for open contact and closed contact.	2	<i>K</i> 2	CO2	
	Write the structured text instruction for any two logical operations.	2	K2	CO2	
17.	What are the tasks performed by microprocessor in DDC?	2	<i>K1</i>	CO3	
K1 -	Remember; K2 – Understand; K3 – Apply; K4 – Analyze; K5 – Evaluate; K6 – Create		1342	22	
111	Temento, 12 Oraciona, 10 Approximation to Drawing, 10 Orac		107		

4.0			2	K1	CO3	
	18. Mention the two algorithms used in DDC software.					
	9. What is the importance of distributed architecture over centralized architecture?					
	0. What is a Shared communication facility in DCS?					
	21. Distinguish the local server and remote server. 22. List out the advantages of IOT.					
22.	List of	it the advantages of 101.	2	K2	CO5	
		$PART - C (6 \times 11 = 66 Marks)$				
22		Answer ALL Questions	1.1	W2	CO.1	
23.	a)	What is a PLC and explain with neat diagram the architecture of PLC. OR	11	K2	CO1	
	b)	Write a ladder logic program to implement the following sequence	11	<i>K</i> 2	CO1	
		• Normally open push button and normally closed push button are used to start and stop the process.				
		• When the start button is pressed, solenoid A energizes to start filling the tank.				
		• As the tank fills the empty level sensor switch closes.				
		• When the tank is full the full level sensor switch closes.				
		Solenoid A is de-energized.				
		• The agitator motor starts automatically and runs for three minutes to mix the liquid.				
		• When the agitator motor stops solenoid B is energized to empty the tank.				
		• When the tank is completely empty the empty sensor switch opens to de				
		energize solenoid B.				
		The start button is pressed to repeat the sequence.				
2.4	\		11	<i>K3</i>	CO2	
24.	a)	Construct a transition and action with regards to sequential function chart (SFC). OR	11	K.S	CO2	
	b)	What is instruction list programming in PLC? i) List out the various operators in	11	<i>K3</i>	CO2	
	0)	instruction list and describe them. ii) Develop a minimum of five logical operations				
		in ladder logic programming and implement its equivalent instruction list program.				
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25.	a)	What is SCADA? Explain in detail the various functional blocks of SCADA.	11	K2	CO3	
		OR				
	b)	What are the major functions of data acquisition system? Explain the various block	11	K2	CO3	
		of data acquisition system in detail.				
26	۵)	Cive a detailed associated an Distributed control system was for an association	11	K2	CO4	
26.	a)	Give a detailed case study on Distributed control system use for process industry. OR	11	MZ	004	
	b)	Describe in detail the evolution of DCS along with its architecture supported by a	11	K2	CO4	
	0)	neat diagram.				
27.	a)	Discuss in detail about the cloud based automation with typical application.	11	K2	CO5	
		OR				
	b)	Describe in detail about Internet of things with neat sketch and also summarize the	11	<i>K</i> 2	CO5	
		various applications of IoT.				
20	a) (i)	Compare the low level and High level human interface in DCS	6	K2	CO4	
28.	a) (i)	Compare the low level and High level human interface in DCS What is safety PLC? Describe the necessity of safety PLC in detail.	5	K2	CO5	
	(11)	OR	-			
	b) (i)	Discuss about the different configurations of Local Control Unit with neat diagram.	6	<i>K</i> 2	CO4	
		Discuss the various levels or hierarchy in a networked control system.	5	K2	CO5	
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